



Cinema Pro JR-K5

Operations Manual



BEFORE YOU START, READ THESE WARNINGS

- 1) **ONLY USE VARIZOOM POWER SOURCES AND CABLES. USING DIFFERENT POWER COMPONENTS CAN LEAD TO SEVERE DAMAGE TO THE HEAD AND EVEN THE CAMERA. THIS TYPE OF DAMAGE IS NOT COVERED UNDER WARRANTY.**
- 2) **TURN OFF POWER WHEN NOT IN USE. DO NOT LEAVE STATIONARY HEAD POWERED UP FOR EXTENDED PERIODS OR THE MOTORS MAY SEIZE AND THIS IS NOT COVERED BY WARRANTY**
- 3) **ALWAYS BALANCE THE CAMERA ON THE PLATFORM BOTH HORIZONTALLY AND VERTICALLY.**
- 4) DO NOT MODIFY THE SUPPLIED CABLES OR ATTEMPT TO DISASSEMBLE THE HEAD.
- 5) DO NOT GET THE SYSTEM WET – IT IS NOT WATERPROOF.
- 6) ALWAYS MAKE SURE YOUR LENS AND POWER CABLES HAVE ENOUGH SLACK RUNNING THROUGH THE TILT AXIS TO PREVENT TWISTING AND TEARING OF THE CABLES.
- 7) MAKE SURE YOUR LENS CLEARS THE BASE OF THE HEAD WHEN TILTING. IF THE LENS DOES NOT CLEAR THE BASE, SET SOFT LIMITS (SECTION 7) TO PREVENT THE LENS FROM STRIKING THE BASE OF THE HEAD WHEN TILTING.

General Description

The CinemaPro JR is a lightweight, two-axis motion control head for film and video cameras. It has a wide variety of operating modes: manual operation from joystick, **motion control style record and playback**, **“go to mark” preset framing***. Software upgrade options are also available for additional features such as intervalometer, camera sync, PC data share, and additional recorded takes and mark points.

The Cinema Pro JR’s optional advanced Controller can give the user all input and programming capabilities and has a joystick for pan & tilt control. The Advanced Controller also works in concert with two optional control input devices: Pan Bars for broadcast-style operation or Hand Wheels for cinema-style operation.

The Jibstick remote is a simpler, less expensive controller designed for one-man jib operation. The jibstick only offers joystick pan & tilt with smoothing and speed control.

The Cinema Pro JR’s lens interface controls zoom and focus. It handles several control signals: RS-232 for Fujinon digital lenses or Varizoom (TOC) motor drives, RS-422 for Canon digital lenses or Preston motor drives, position or speed based analog, pulse width type RC servos, and LANC.

***Go to marks and presets are only available when using the advanced controller.**

1. Basic Setup

-Secure the head to crane, tripod, or solid mounting beam

-Plug the FACTORY POWER SUPPLY into AC mains

-Connect XLR cable between head and FACTORY POWER SUPPLY

-Plug green control cable into the head and the jack marked "CTRL" on the Advanced Controller (or Jibstick, if applicable)

-If applicable, connect camera power (red) and lens control (orange) and route the cables through the tilt axis port hole to connect to your camera

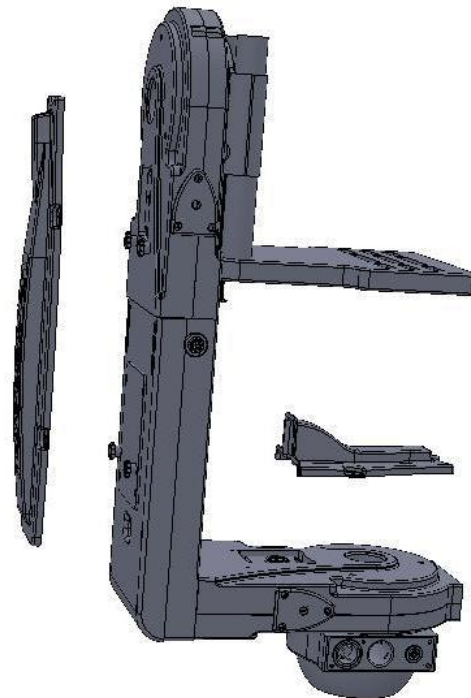
-Make sure to turn camera power on as the LAST step.



cables

Feeding External Cables through the Head

In some cases, you will need to feed video or other cables through the head. To do so, simply remove the cable covers (pictured at right, covers may differ slightly in appearance). 4 screws secure the long vertical cable cover, while only 2 screws secure the short horizontal cover. Run the cables through the pan base and tilt arm with enough slack, and reattach the cable covers.



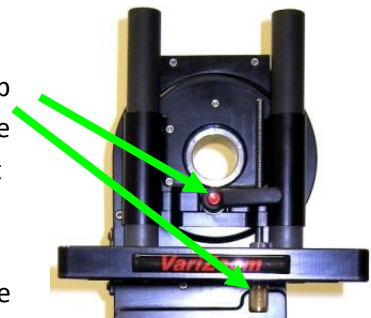
If using the TOC system

Connect the TOC 3A (3 axis lens drive box) between the orange 16-PIN lens control connector located on the head, and the grey "control" connector located on the TOC 3A. Connect the Lens drive motors to the appropriate connection according to their function (zoom, focus, iris)

Balance the Camera – Although the head will hold position very well, it operates best when the camera is balanced on the mounting platform. With heavier cameras, it is essential, as an out-of-balance load will cause the servos to constantly fight to hold position. **Make sure that the motor power is turned off before balancing. This will allow you to move the tilt axis by hand.** To balance the camera horizontally, you need to place the camera's front-to-back center of mass at the center of the mounting platform slot. You can do this by trial and error, sliding the camera front-to-back on the mounting platform until it stays level. The simplest accurate way to find the camera's center of mass is to lay a pencil/pen on a table and try to balance the camera on it front-to-back. The spot on the camera where it comes closest to balancing on the pencil is the center of mass. Place the camera's center of mass at the center of the mounting slot and secure the camera with mounting screws (2 if possible). When horizontally balanced, the platform should stay level.



To get the vertical balance right, raise or lower the platform to get the camera's vertical center of mass located on the center of tilt rotation. To adjust, loosen the platform locking lever about ½ turn. Turn the black knob on the underside of the platform to precisely raise or lower it – you can use a hex key. Try to get the camera's center of mass right on the center of tilt rotation. Rotate the platform to various angles and adjust until it holds position at any angle. If it falls down, you need to adjust the platform upward. If it drifts upward, you need to lower the platform. When balance is achieved, tighten the platform locking lever.



After all connections have been made and the camera is balanced, the head is ready to be powered up.

Connect the power supply to AC power. Plug in the green communication connector to the head, and the other end to the jibstick. The jibstick should now power up. Once the Sync light is illuminated, you may then turn on the motor power switch.



2. Jibstick layout and functions



Communication connector (Green)- Connect this to the communication cable, and connect the other end of the communication cable to the green connector on the CinemaPro Head. This cable runs communication as well as power to the controller from the head, so make sure that there is XLR power connected to the CinemaPro. **Note: If you disconnect this green communication cable, you must also disconnect power or the head may not sync to the controller again.**

Pan direction and Tilt direction- Reverses the response direction for each axis

Joystick for pan and tilt operation- Move the joystick in the direction you wish the head to move. The response direction can be changed with the response direction switches.

Smoothing- Adjusts the amount of smoothing for both the pan and tilt axes. The higher the smoothing is set, the more dampened or 'ramped' the response will be. It adjusts the acceleration/deceleration curve.

Pan speed and Tilt Speed- Adjusts the maximum speed for the pan motor and tilt motor.

Deadband- Adjusts the amount the joystick must be moved before pan and tilt will respond.

3. Troubleshooting

No Response from head

- 1) Make sure that the motor power switch is turned on, and the light above it is green.
- 2) Check to make sure that there aren't any soft limits set too close together. Disable all soft limits, and then try again.
- 3) Power down the system, unplug the XLR connector, wait for a few seconds, re-plug everything back in, power it back up, then try again.

Pan and Tilt moves too slowly or PanBar range is limited

- 1) Check both speed settings. If the speed is dialed too slowly it will appear to have no response at all.

Head is "jerky" or too responsive

- 1) Turn down motor speed.
- 5) If you have been using the advanced controller, check to make sure that the servo tuning in the "tuning" menu is set to the factory setting. Selecting "reset all" will return this to the factory preset.

Note: When the jibstick is plugged into the head, it will default to the servo tuning of the last advanced controller that used with the head.

My jib or crane sways, swims, moves around when the head is rotating

- 1) This is a problem of imbalance in rotational inertia. If the jib moves when panning, you need to attach the optional counterweight. If the jib move around when tilting, you need to adjust the

vertical balance (adjust the camera platform until the camera's center of gravity is on the center of tilt rotation.

Head moves on its own

Cycle power and do not touch the joystick when powering up the system. The joystick has to calibrate on power-up, so if it's off-center then it will calibrate incorrectly.

4. Options and Specs

Additional Software- The controller can be upgraded to have more position marks, intervalometer mode, and additional recorded moves.

Additional Head options-

The Head can be fitted with either a 100mm half ball or Mitchell mount. A Mitchell ring adapter is available for old style Mitchell mount.

An adapter is also available to adapt Mitchell mount to Jimmy Jib style mount.

Wireless control is available, and operates up to ¼ mile. (1 mile with line of sight).

Additional controller cables are available in 50', 100', or 150' increments. A coupler is available to join the cables, or we will make a cable of any reasonable length as a custom item on request.

Head XLR power cables are available in standard 30' or 75' increments, or longer as a custom item on request.

External Lens Drive Motors available for separate purchase

Specs-

Head construction: Primarily Aluminum, with carbon fiber platform rails and some stainless steel, steel, brass, bronze and delrin components

Height: 20.5"

Width: 11.3"

Depth: 6"

Weight: 13lbs

Camera weight limit: 35lbs

Maximum speed: 130 deg/sec (limited for optimal performance)

Power Supply (included): 24VDC, 5A

Head Power Requirements: 24 VDC regulated, 120 watts max

WARNING: Do not connect the head to any power supply other than the one supplied. If you must power the head another way, make sure you clear it with VariZoom first.

Connectors-

Head Base connectors

Controller - 7pin LEMO (green)

XLR 4-pin Head/Camera Power

Passageway for external cables (video, lens control, etc.)

Head Top connectors

Lens Control Out to camera/lens/lens drive - 16pin LEMO (orange)

Camera Power Out - 2pin LEMO (red)

Controller connectors

CTRL - 7Pin LEMO – Head control cable (green)

SERIAL - 8pin LEMO – TOC or Preston Lens Drive Hand Units (gray)

ANALOG - 5pin LEMO – Pan Bars zoom & focus controls (white)

Jib Counterweight Option

Some lightweight jibs may not have enough mass to neutralize the high acceleration and torque of the CP Jr head. If the motion of the head causes your jib to sway from side to side in a way you want to eliminate, we have a counterweight option that will effectively eliminate the problem.

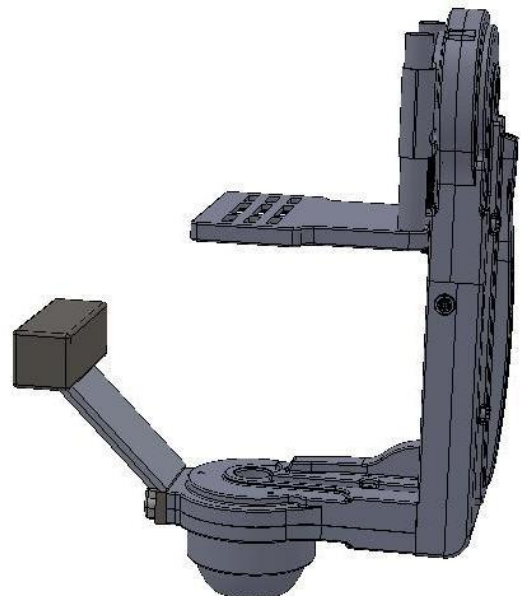
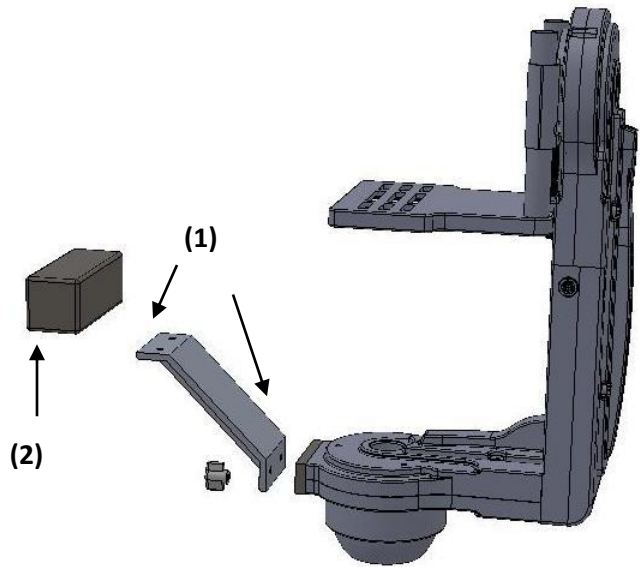
Heavier jibs will not be affected much, and the effect is only significant during sudden moves. Adding our counterweight to the CP Jr balances out the rotational inertia so even lightweight jibs will not be susceptible to the swaying effect caused by sudden moves.

Attaching the counterweight is simple. Before attaching the counterweight, fix the head to your jib.

(1) Start by attaching the interface plate to the head with the 4 small screws (supplied). Now fix the support arm to the interface plate using the supplied thumbscrews, lockwashers, and flat washers. Put the flat washers between the support arm and the lockwashers to prevent scratching. Tighten the thumbscrews thoroughly.

(2) Now attach the square weight to the support arm, using the same type of thumbscrews, lockwashers and washers. Tighten the thumbscrews thoroughly.

The counterweight adds about 7 lbs total weight to the system, so if you don't need it, try operating without it first. Also note that some swaying may be caused by the camera platform being out of vertical balance – remedy



this by adjusting the camera platform up or down so the camera's center of mass is on the center of tilt rotation.

Appendix

24VDC Power Supply Connector

1) Power Supply Connector - XLR 4-pin Female

Pin	Function	Wire Color
1	N.C.	
2	CP JR Neg.	Black & Green
3	CP JR Pos.	White & Red
4	N.C.	

* 2) Optional XLR Y-adapter for running head AND camera power through single XLR extension

Y-1 "Camera" Power Input Male XLR Connector

Pin	Function
1	Camera Neg.
2	N.C
3	N.C.
4	Camera Pos.

Y-2 "Head" Power Input Male XLR Connector

Pin	Function
1	N.C.
2	CP JR Neg.
3	CP JR Pos.
4	N.C.

Y-Single Female XLR Output Connector (combines Camera & Head Power into one XLR cable run - connect to 30' XLR extension that plugs into CP JR head)

Pin	Function
1	Camera Neg.
2	CP JR Neg.
3	CP JR Pos.
4	Camera Pos.

CP JR Head - Base Connectors

1) Head Control Connector (Green) - LEMO EGG1B307CLL

Pin	Function	Wire Color (Cable)	
1	Common	Brown	
2	RS-422 RXD	Red	
3	RS-422 RXD!	Orange	
4	RS-422 TXD	Yellow	
5	RS-422 TXD!	Green	
6	24 VDC +	Blue	Power to Remote or Jibstick
7	24 VDC -	Violet	Power to Remote or Jibstick

2) Power Input Connector - XLR 4-pin Male

Pin	Function	Wire Color
1	Camera Neg.	Black
2	Cinema Pro Neg.	White
3	Cinema Pro Pos.	Red
4	Camera Pos.	Green

***** WARNING: DO NOT POWER THE CINEMAPRO JR WITH ANYTHING OTHER THAN THE INCLUDED FACTORY POWER SUPPLY OR YOUR WARRANTY MAY BE VOIDED. THE UNIT MAY BE SEVERELY DAMAGED AND CAUSE DAMAGE TO YOUR CAMERA IF YOU USE A NON-APPROVED POWER SUPPLY. IF YOU MUST POWER IT USING A BATTERY SYSTEM, MAKE SURE THE SETUP IS APPROVED BY VARIZOOM AND EXECUTED BY A QUALIFIED TECHNICIAN.**

CP JR Head - Top Connectors

1) Camera Power (Red) - LEMO EGG2B302CLL

Pin	Function
1	Camera Power +
2	Camera Power -



2) Lens Control (Orange) - LEMO EGG2B316CLL (Final Version)

Pin	Function	Lens Connection
1	RS-232 RXD	Fuji Digital
2	RS-232 TXD	Fuji Digital
3	+5 VDC - Iso	Fuji Digital
4	Common - Iso	Fuji Digital
5	RS-422 RXD	Canon Digital
6	RS-422 RXD!	Canon Digital
7	RS-422 TXD	Canon Digital
8	RS-422 TXD!	Canon Digital
9	Common	
10	+5 VDC	
11	Analog #1	Zoom
12	Analog #2	Focus
13	Camera Run	
14	Camera Run	
15	24 VDC +	
16	24 VDC -	



Lens Connection Table

Lens Control, 16 pin LEMO FGG2B316CLAD

	Fujinon Digital	Fujinon Analog	Fujinon Telecon	Canon Digital	Canon Analog
	HR10A-10P-10P	HR10A-10P-12P	HR10A-10J-12P	HR25-9P-20P	HR25-9P-20P
1 RS-232 RXD	3				
2 RS-232 TXD	2				
3 Iso Vcc	4				
4 IsoCom & IsoCom3	5			19 & 20 - Green	
5 RS-422 RXD				17 - Orange	
6 RS-422 RXD!				18 - Yellow	
7 RS-422 TXD				15 - Brown	
8 RS-422 TXD!				16 - Red	
9 Common		2	3		20
10 Vcc (5 volts)					
11 Analog #1 out		7 (If zoom)	9 (Zoom)		2
12 Analog #2 out		7 (If focus)	8 (focus)		3
13 RC Servo Out 1					
14 RC Servo Out 2					
15 Head power + out					
16 Head power - out					

Tie pins 1 & 2 to 7

for position control

Advanced Controller Connectors (if applicable)

1) Auxiliary power input

1	Center 18 to 36 volts input
2	Common

2) "CTRL" - Head Control (Green) - LEMO EGG1B307CLL

Pin	Function	Wire Color (Cable)	
1	Common	Brown	
2	RS-422 RXD	Red	
3	RS-422 RXD!	Orange	
4	RS-422 TXD	Yellow	
5	RS-422 TXD!	Green	
6	24 VDC +	Blue	Power from Cinema Pro
7	24 VDC -	Violet	Power from Cinema Pro

2) "SERIAL" - Peripheral Connector (Gray) - EGG1B308CLL

Pin	Function
1	Common
2	#1 RS-232 RXD
3	#1 RS-232 TXD
4	+5 VDC
5	24 VDC -
6	#2 RS-232 RXD
7	#2 RS-232 TXD
8	24 VDC +

3) "ANALOG" - Panbars Option Zoom & Focus Input (White) - EGG1B305CLL

1	Common
2	Motor disable
3	Zoom analog signal
4	Focus analog signal
5	+5 VDC

4) "WHEELS" - Wheels and Panbars Option Input (Blue) - EGG1B306CLL

1	Common
2	+5 VDC
3	Pan encoder signal "A"
4	Pan encoder signal "B"
5	Tilt encoder signal "A"
6	Tilt encoder signal "B"

5) "BLOOP" - Sync & Bloop - Fischer D103A056-130

1	Common - Isolated
2	+5 VDC - Isolated
3	Sync In
5	Bloop out #1
7	Bloop out #2

6) "VIDEO SYNC" - BNC

1	BNC signal
2	Isolated common

Jibstick Connectors (if applicable)

1) Cinema Pro Control (Green)- LEMO EGG1B307CLL

Pin	Function	Wire Color (Cable)	
1	Common	Brown	
2	RS-422 RXD	Red	
3	RS-422 RXD!	Orange	
4	RS-422 TXD	Yellow	
5	RS-422 TXD!	Green	
6	24 VDC +	Blue	Power from Cinema Pro
7	24 VDC -	Violet	Power from Cinema Pro

2) Focus Input - Fischer D103A054-130

1	Common
2	+5 VDC
3	Focus analog signal
4	Zoom analog signal (unused)

Common